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tors, we rely on the synthesis of “artificial trajectories” from the given sample of trajectories, and show that this idea opens new avenues for designing and analyzing algorithms for batch mode reinforcement learning.

Keywords Reinforcement learning ·

Optimal control · Artificial trajectories ·

Function approximators 1 Introduction

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Szepesvári June 9, 2009 Contents 1
Overview 3 2 Markov decision processes
7

Neural reinforcement learning for
behaviour synthesis

The goal in reinforcement learning is to
develop efficient learning algorithms, as

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well as to understand the algorithms' merits and limitations. Reinforcement learning is of great interest because of the large number of practical applications that it can be used to address, ranging from problems in artificial intelligence to operations research or control engineering.

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Intelligence And Synthesis with
Reinforcement Learning

Reinforcement Learning is a subset of machine learning. It enables an agent to learn through the consequences of actions in a specific environment. It can be used to teach a robot new tricks, for example. Reinforcement learning is a

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behavioral learning model where the algorithm provides data analysis feedback, directing the user to the best result.

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For this purpose, numerous

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reinforcement learning algorithms are available (e.g. TD(λ), AHC [5]), among which the Q-learning method is certainly the most used.

2.2 Q-learning

Reinforcement learning synthesises a mapping function between situations and actions by maximising a reinforcement signal. Q-learning [6] algorithms store the expected

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Reinforcement Learning and Distributed
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Synthesis, Reinforcement Learning,
SARSA, Motion Blending 1 Introduction In
an environment where humans have to
quickly conduct one motion after
another, they adapt their behaviours

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and prepare for the next motion while approaching the target. This allows smooth transition to the target action, as well as a quicker activation to interact with ...

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theory of dynamic programming We give
a fairly comprehensive catalog of
learning problems describe the core
ideas note a large number of state of the
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I have discussed some basic concepts of Q-learning, SARSA, DQN , and DDPG. In the next article, I will continue to discuss other state-of-the-art Reinforcement Learning algorithms, including NAF, A3C... etc. In the end, I will briefly

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compare each of the algorithms that I have discussed.

Introduction to Various Reinforcement Learning Algorithms ...

Program Synthesis using Deduction-Guided Reinforcement Learning 3 ment learning algorithm that can improve the

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policy based on such additional feedback from the deduction engine. As shown schematically in Figure 1, our synthesis algorithm consists of three conceptual elements, indicated as "Take action", "Deduce", and "Update policy".

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algorithms to infer dynamics from online
experiments [1].

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... In this book we focus on those
algorithms of reinforcement learning
which build on the powerful theory of
dynamic ...

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Reinforcement Learning and 9 examples
of what you can do ...

A popular algorithm, Q-learning [9], is an off-policy variant of TD learning. In an off-policy algorithm, the policy that the agent follows to interact with the environment (behavior policy) is

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independent of the optimal policy that the agent aims to learn (target policy). To see the TABLE I Comparisons of value-based reinforcement learning ...

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The goal in reinforcement learning is to develop efficient learning algorithms, as well as to understand the algorithms' merits and limitations. Reinforcement learning is of great interest because of the large number of practical applications that it can be used to address, ranging from problems in artificial intelligence to operations

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research or control engineering.

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standable by a reinforcement learning agent, and formulate a feature set extracted from the AIG characteristics. In addition, we derive a novel multi-

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objective reward function that aids the agent in minimizing the area subject to a delay constraint. We introduce DRiLLS (Deep Reinforcement Learning-based Logic Synthesis), a novel framework based on

An Inductive Synthesis Framework for

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In reinforcement learning much of the burden is moved from the teacher to the training algorithm. The exact and general algorithms that exist for these problems are based on dynamic programming (DP), and have a computational complexity that grows exponentially with the dimensionality of

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the state space.
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Algorithms for reinforcement learning [electronic resource]...
The authors have used A2C reinforcement learning algorithm to determine the order of applying optimization commands (among a few candidate commands) to a given circuit for achieving better QoR.

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